

**Call For Papers**

**The 49<sup>th</sup> ISR**

**(International Symposium on Robotics)**

# The 49<sup>th</sup> ISR (International Symposium on Robotics)

## Theme

DEPLOYABLE INTELLIGENT ROBOTS – Technologies and Best Practices for integrating AI in robot systems and for facilitating easy deployment of robots in broad applications.

## Date and Venue

Date: July 6-7, 2017

Venue: National Exhibition and Convention Center (Shanghai)

## Organization Chart

### Advisory Committee

- Hegao Cai, Chinese Academy of Engineering , China
- Xisheng Feng, Shenyang Institute of Automation Chinese Academy of Sciences, China
- Youlun Xiong, Chinese Academy of Sciences , China
- Bo Zhang, Chinese Academy of Sciences, China
- Nanning Zheng, Chinese Academy of Engineering , China
- Yangsheng Xu, The Chinese University of Hong Kong, China

### Technical Program Committee

#### Chair

- Tianran Wang, Chinese Academy of Engineering, China

#### Co-Chairs

- Tianmiao Wang, Beihang University, China
- Jie Zhao, China Harbin Institute Of Technology, China

#### Members

- Ussamma Khatib, Stanford University, USA
- Dezhen Song, Texas A&M University, USA
- Shigang Yue, University of Lincoln, UK

- Kaspar Althoefer, Queen Mary University of London, UK
- Alois Knoll, TU Munich, Germany
- Rainer Bischoff, KUKA, Germany
- Veronique Perdereau Paris IV University, France
- Shaoping Bai, University of Aalborg, Denmark
- Hongliang Ren, National University of Singapore
- Georg Rauter, University of Basel, Switzerland
- Toshio Fukuda, University of Nagoya, Japan
- Xiaoping Chen, University Of Science And Technology Of China, China
- Zexiang Li, The Hong Kong University of Science and Technology, China
- Yaonan Wang, Hunan University, China
- Qiang Huang ,Beijing Institute Of Technology, China
- Shuzhi Ge ,University Of Electronic Science And Technology Of China, China
- Tian Huang ,Tianjin University, China
- Jingtai Liu ,Nankai University, China
- Jianda Han ,Shenyang Institute of Automation Chinese Academy of Sciences, China
- Xiangyang Zhu, Shanghai Jiao Tong University, China
- Jinsong Ouyang ,Instrumentation Technology and Economy Institute, China
- Caihua Xiong, Huazhong UST, China
- Rong Xiong, Zhejiang University, China
- Hong Cheng, Chengdu University of Electronics Technologies, China
- Zengguang Hou, Institute of Automation, Beijing, China
- Rong Liu, Beihang University, China
- Hongguang Wang, Institute of Automation, Shenyang, CAS, China
- Ming Liu, City University of Hong Kong, China
- Fuchun Sun, Tsinghua University, China
- Guangming Xie, Peking University, China
- Jiqiang Song, Intel Labs China, ILC, China
- Gansha Wu, Uisee Technology (Beijing) Ltd, China
- Fengshan Zou, Shenyang Institute of Automation Chinese Academy of Sciences, China
- Yanliang Zhang, Googol Technology(Shenzhen) LtdJingguo Ge, EFORT Intelligent Equipment Co., Ltd, China
- Zhaoxiong Huang, Changsha Chaint Robotics Co., Ltd, China
- Wenming Jiang, GSK CNC Equipment Co., Ltd, China
- Tong Wu, SINOMACH Intelligence Technology CO.,Ltd, China
- Erbin Liu, Guangzhou Risong Intelligent Technology Holding Co., Ltd, China
- Yanjie Liu, Harbin Boshi Automation Co., Ltd, China
- Zhenzhong Yu, HIT Robot Group Co.,Ltd, China
- Jihu Wang, Estun Robotics Co., Ltd, China
- Lixin Ma, Codesys Software System(Beijing) Co., Ltd, China
- Jianhai Li, Qingdao Haier Robotics Co., Ltd, China
- Xianzheng Li, Tangshan Kaiyuan Robot System Co., Ltd, China
- Baohai Cao, WITTENSTEIN (Hangzhou) Co. Ltd, China
- Gang Liu, Xi'an Aerospace Precision Electromechanical Institute(No.16 Institute) , China

- Guanglin Li, Shenzhen Institutes of Advanced Technology, Chinese Academy of Sciences, China
- Aiguo Wang, Shanghai Electrical Apparatus Research Institute(Group)Co.,Ltd, China
- Lianqing Liu, Shenyang Institute of Automation Chinese Academy of Sciences, China
- Guotian He, Chongqing Dexin Robot Testing Center Co.,Ltd, China
- Luping Chen, Research Center for Computer and Microelectronics Development of MIIT, China
- Weiguo Hou, Wuhu CEPREI Robotics Industry Technology Research Institute Co. Ltd, China

## **International organizing committee**

### **Chair**

- Daokui Qu, China Robot Industry Alliance, China

### **Co-Chairs**

- Jianwei Zhang, University of Hamburg, Germany
- Jong-Oh Park, Chonnam National University, Korea

### **Regional Publicity Chairs**

- Joe Gemma, International Federation of Robotics, USA
- Haibin Yu, Shenyang Institute of Automation Chinese Academy of Sciences, China
- Johnny Kim, KAR - Korea Association of Robot Industry, Korea
- Jeff Burnstein, RIA - Robotic Industries Association, USA
- Hiroshi Fujiwara, JARA - Japan Robot Association, Japan
- Patrick Schwarzkopf, VDMA Robotics+Automation, Germany
- Vitaly Nedelskiy, RAR - Russian Association of Robotics, Russian
- Ren C. Luo, National Taiwan University, Taiwan

## **Organizing Committee**

### **Chair**

- Xiaogang Song, China Robot Industry Alliance, China

### **Co-Chair**

- Yucheng Hao, China Robot Industry Alliance, China

### **Members**

- Jintao Wang, SHENYANG SIASUN ROBOT&AUTOMATION CO.,LTD, China
- Hui Zeng, EFORT Intelligent Equipment Co., Ltd, China
- Hong Wu, Googol Technology(Shenzhen) Ltd, China
- Hongji Li, GSK CNC Equipment Co., Ltd, China
- Qing Fan, SINOMACH Intelligence Technology CO.,Ltd, China

- Xiaodong Wu, Shanghai Electrical Apparatus Research Institute(Group)Co.,Ltd, China
- Zhiqiang Sun, Guangzhou Risong Intelligent Technology Holding Co., Ltd, China
- Jianxun Tan, Harbin Boshi Automation Co., Ltd, China
- Jiegao Wang, Estun Robotics Co., Ltd, China
- Xiaowei Li, Codesys Software System(Beijing) Co., Ltd, China
- Sai Xie, Changsha Chaint Robotics Co., Ltd, China
- Tao Wang, Qingdao Haier Robotics Co., Ltd, China
- Xianzheng Li, Tangshan Kaiyuan Robot System Co., Ltd, China
- Lei Hai, WITTENSTEIN (Hangzhou) Co. Ltd, China
- Junyun Shang, Xi'an Aerospace Precision Electromechanical Institute(No.16 Institute) , China
- Yalei Bi, Shenzhen Institutes of Advanced Technology, Chinese Academy of Sciences, China
- Jianda Han, Shenyang Institute of Automation Chinese Academy of Sciences, China
- Zhenzhi Yao, Research Center for Computer and Microelectronics Development of MIIT, China
- Xiao Li, Wuhu CEPREI Robotics Industry Technology Research Institute Co. Ltd, China

## **CALL FOR ABSTRACT**

### **Topics**

The symposium is based on industrial requirements. Industrial papers related to applications and case studies are welcome. Original contributions on topics related (but not limited) to the following are invited:

#### **1. Design Methodology**

- modeling, planning and control
- mechanisms and kinematics
- calibration and identification
- AI and Robotics (learning/ adaptation, reasoning, cloud, etc.)

#### **2. Components & Technologies**

- sensors (vision / tactile / auditory)
- visual servoing and tracking
- actuators and controllers
- robot end-effectors / robot infrastructure
- materials

#### **3. System Integration**

- autonomous vehicles (land, sea, and air)
- mobile manipulation
- collaborative robots / human-robot interaction
- Safety issues
- benchmarking / experimental practices

#### **4. Robotics in Intelligent Manufacturing**

- assembly, handling, painting, machining, processing, logistics etc.
- robot programming and languages
- intelligent manufacturing systems
- safe human-robot-cooperation / cooperating robots

#### **5. Robotics in Service**

- home & office robotics
- SR for professional services
- rescue / surveillance / security / defence robotics
- assistance / rehabilitation / medical robotics
- educational and entertainment robotics
- exploration / space / aerial / underwater robotics

#### **6. Robotics in Innovative Applications**

- food / pharmaceutical / biology robotics
- micro / nano robotics
- network and ubiquitous robotics
- biologically inspired robotics: humanoids / biomimetics / legged robots

#### **7. Platforms, Education, Accelerators**

- standards / testing / assessment
- safety /reliability
- finance/ profitability
- education/ training
- acceleration

### **IMPORTANT DATES**

- Deadline for abstracts: April 30, 2017
- Deadline of acceptance: May 20, 2017
- Deadline for full paper: June 10, 2017

## ABSTRACT SUBMISSION

The official language of the 49<sup>th</sup> ISR is English. Please fill in the form below for your abstract submission.

	中文	英文*
姓名* NAME		
职位* POSITION		
单位(学校)名称* COMPANY (COLLEGE) NAME		
国家* COUNTRY		
所在城市 CITY		
电话* MOBILE PHONE		
E-mail*		
所属的征集范围* AREA OF THE SYMPOSIUM TOPICS		
分享方式*(可多选) PRESENT THE PAPER	<input type="checkbox"/> 演讲 PRESENTATION <input type="checkbox"/> 海报 POSTER	<input type="checkbox"/> 演讲 PRESENTATION <input type="checkbox"/> 海报 POSTER
预计发言的题目* TITLE OF PROPOSED PRESENTATION		
预计发言时长(分钟)* LENGTH OF PRESENTATION (IN MINUTES)		
预计听众会感兴趣的理由* PLEASE LIST THE THREE MAIN POINTS ATTENDEES WOULD LEARN FROM YOUR PRESENTATION	1、_____ 2、_____ 3、_____	1、_____ 2、_____ 3、_____
论文摘要*(不少于 500 字) A BRIEF ABSTRACT		

\*为必填项 NECESSARILY

## NOTICE

1. The abstract shall be submitted no later than April 30, 2017. If your abstract passes the preliminary evaluation, we shall get back to you at your e-mail or by your phone. Then you shall submit the draft of your paper accordingly.

2. The draft paper shall be reviewed by at least two experts from the ISR Technical Program Committee and you will receive feedback on the possible revision of your paper. The ISR

Technical Program Committee is entitled to the sifting and sorting of all papers submitted.

3. The registered author will have the opportunity to present the paper at the National Exhibition and Convention Center (Shanghai) . You may choose from below:

A. Presentation: the author will deliver a 20 minute presentation following a 10 minute Q&A.

B. Poster: the Poster will be displayed at the fixed exhibition area with a fixed size of 1m x 0.8m.

4. In addition to papers, the conference also accepts video, PPT and other forms of contribution.

## **PUBLICATION**

- Accepted papers will be published in the proceedings of the 49th ISR. Selected papers will be published in the Engineering Journal and the Industrial Robot, and the International Journal of Social Robotics.
- In addition to papers, the conference materials will also include accepted video and PPTs, but those will not be published.

## **AWARDS**

- A prestigious certificate will be awarded to each author with a published paper in the proceeding of the 49<sup>th</sup> ISR.
- The best papers selected by the Technical Program Committee will be announced and presented with an award at the Symposium.

## **CONTACT**

论文投稿、会议赞助、媒体合作、会议咨询请与我们联系：  
For questions please contact the 49<sup>th</sup> ISR secretariate at:  
Tel: 86-10-68594830  
E-mail: [cria@mei.net.cn](mailto:cria@mei.net.cn)

